

# Schläuche

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## Rechnung

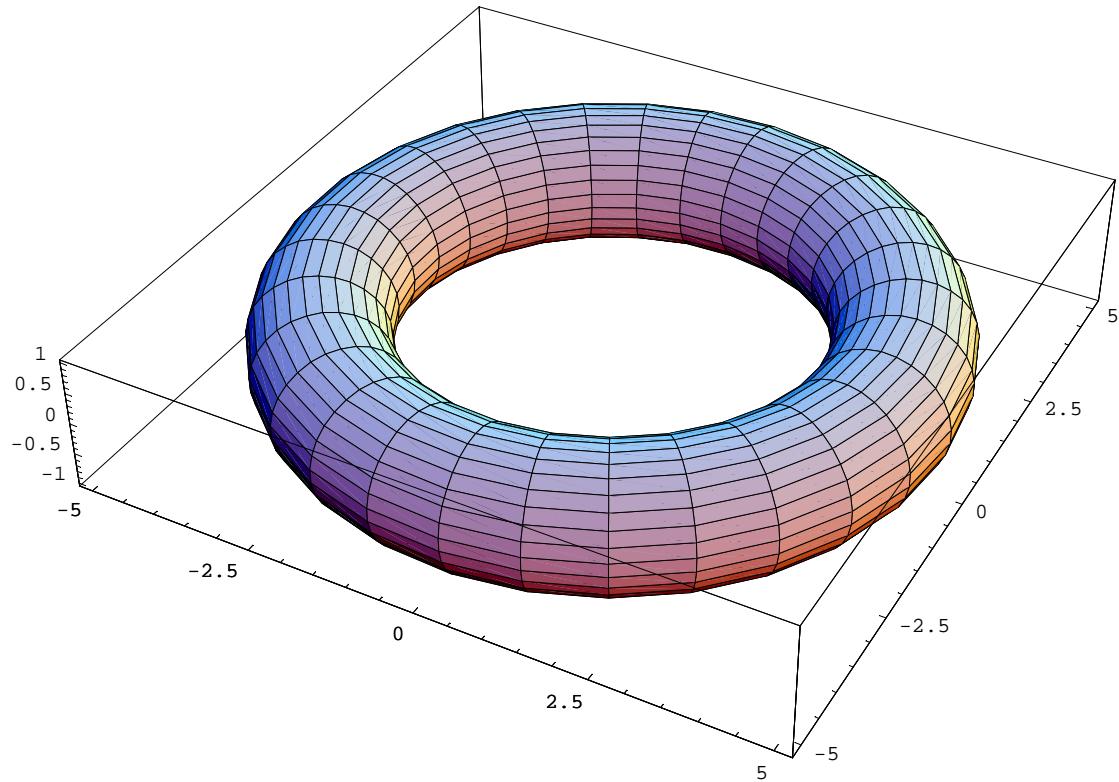
```
Remove["Global`*"];  
  
In[5]:= from[uhu_] := Module[{},  
    (*Rechnung*)  
    v[t_] := {x[t], y[t], z[t]};  
    κ[t_] := Sqrt[  
        ((v''[t].v''[t]) (v'[t].v'[t]) - (v'[t].v''[t])^2) / ((v'[t]).(v'[t]))^3];  
    tT[t_] := v'[t] / Sqrt[v'[t].v'[t]];  
    nN[t_] := 1 / κ[t] 1 / Sqrt[v'[t].v'[t]] D[v'[t] / Sqrt[v'[t].v'[t]], t];  
    bB[t_] := Cross[tT[t], nN[t]];  
    w[t_, φ_] := v[t] + a[t, φ] Cos[φ] nN[t] + b[t, φ] Sin[φ] bB[t];  
    (*Plot*)  
    ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 2 Pi}, {φ, 0, 2 Pi}]];
```

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## Demos Schlauchdefinitionen

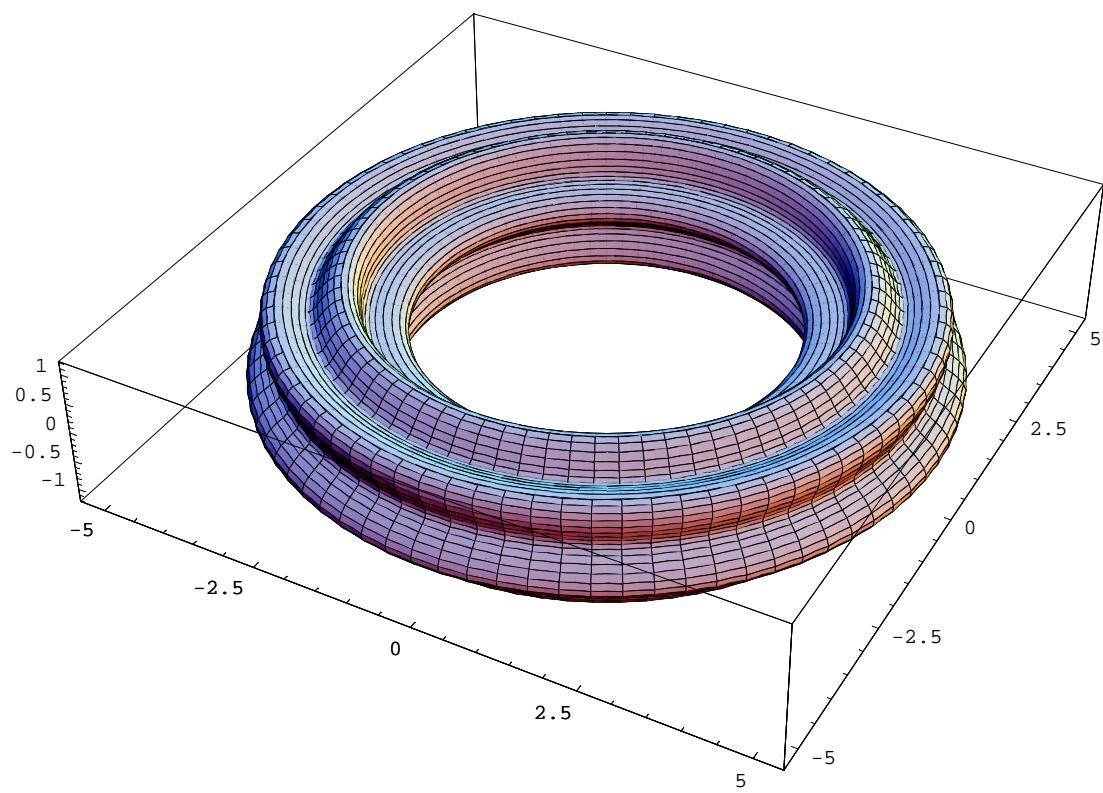
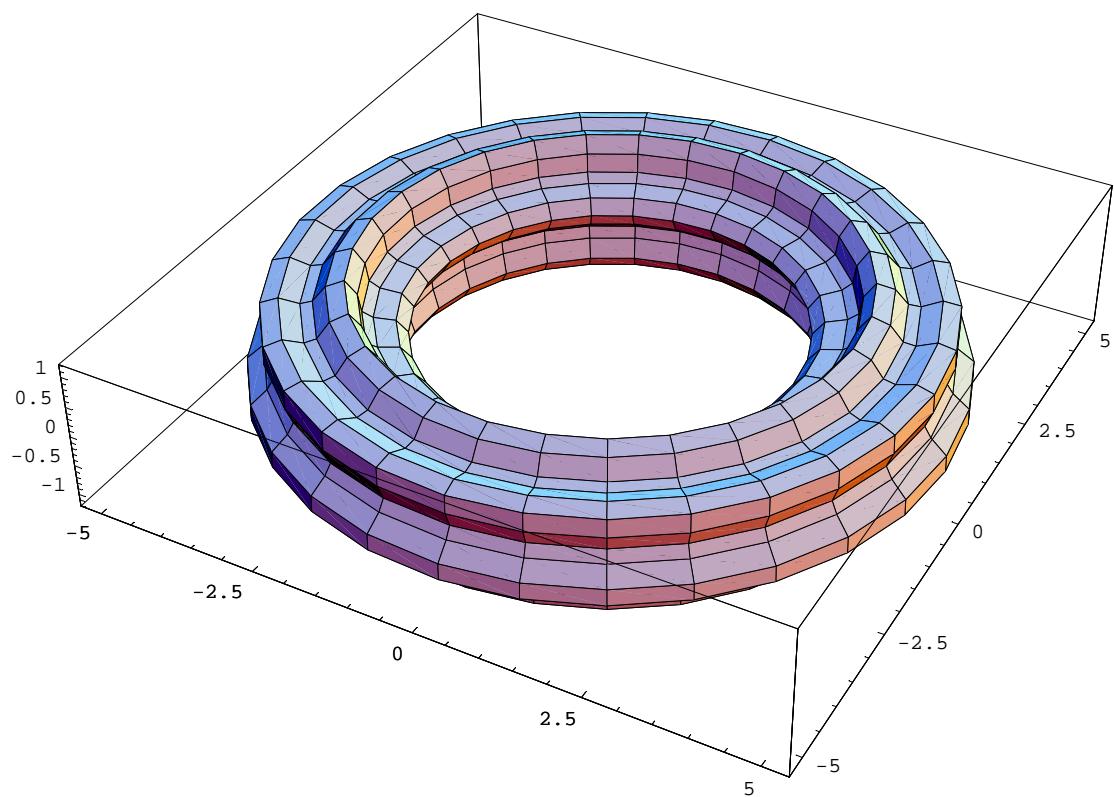
1

```
In[7]:= (*Schlauchdefinitionen*)
x[t_] = 4 Cos[t]; y[t_] := 4 Sin[t]; z[t_] := 0;
a[t_, φ_] := 1; b[t_, φ_] := 1;
from[uhu];
```



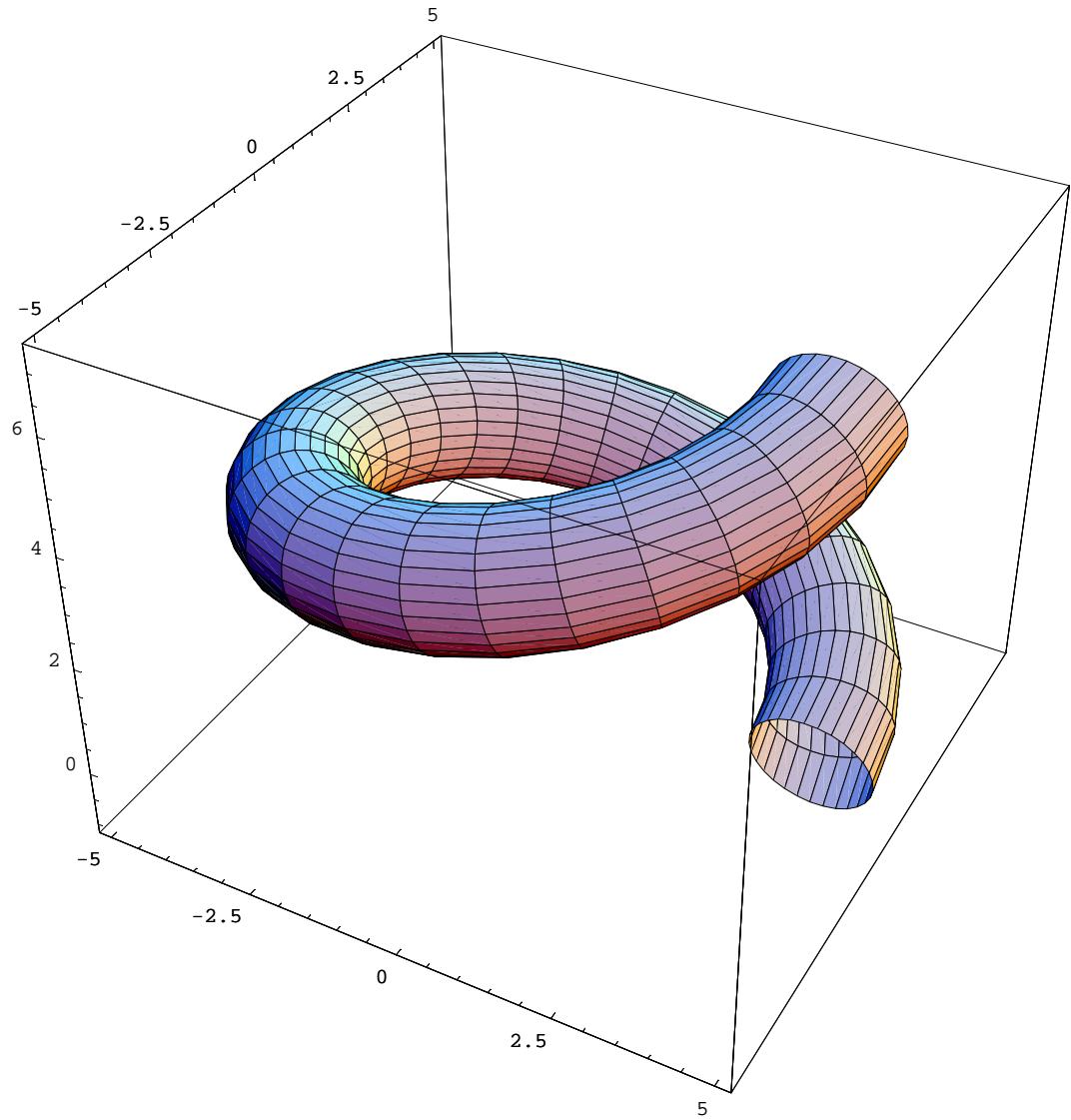
2

```
In[13]:= (*Schlauchdefinitionen*)
x[t_] = 4 Cos[t]; y[t_] := 4 Sin[t]; z[t_] := 0;
a[t_, φ_] := 1 + Sin[6 φ] / 5; b[t_, φ_] := 1 + Sin[6 φ] / 5;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 4 Pi}, {φ, 0, 2 Pi}, PlotPoints → 80];
```

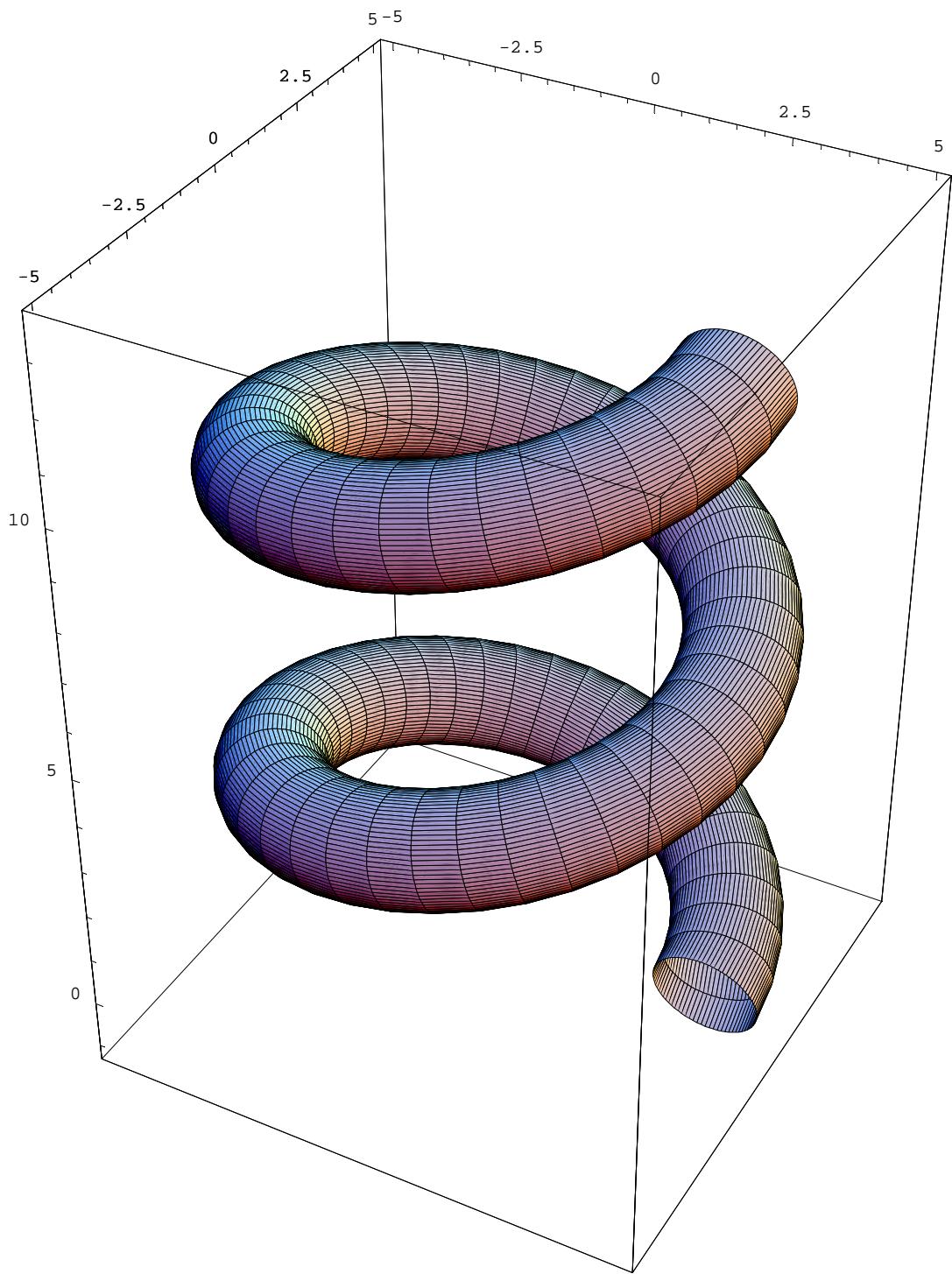


**2**

```
In[17]:= (*Schlauchdefinitionen*)
x[t_]:=4 Cos[t]; y[t_]:=4 Sin[t]; z[t_]:=t;
a[t_,φ_]:=1; b[t_,φ_]:=1;
from[uhu];
```

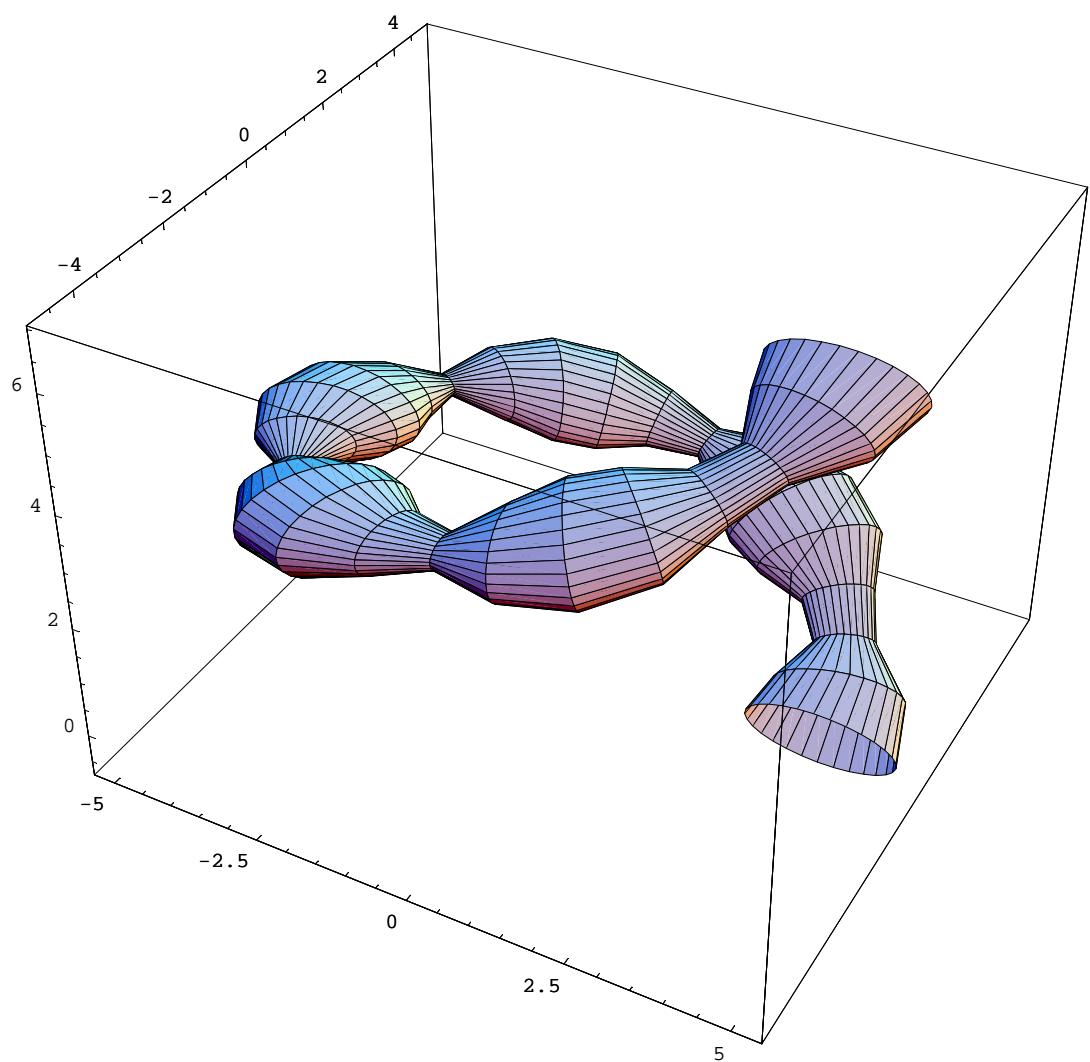


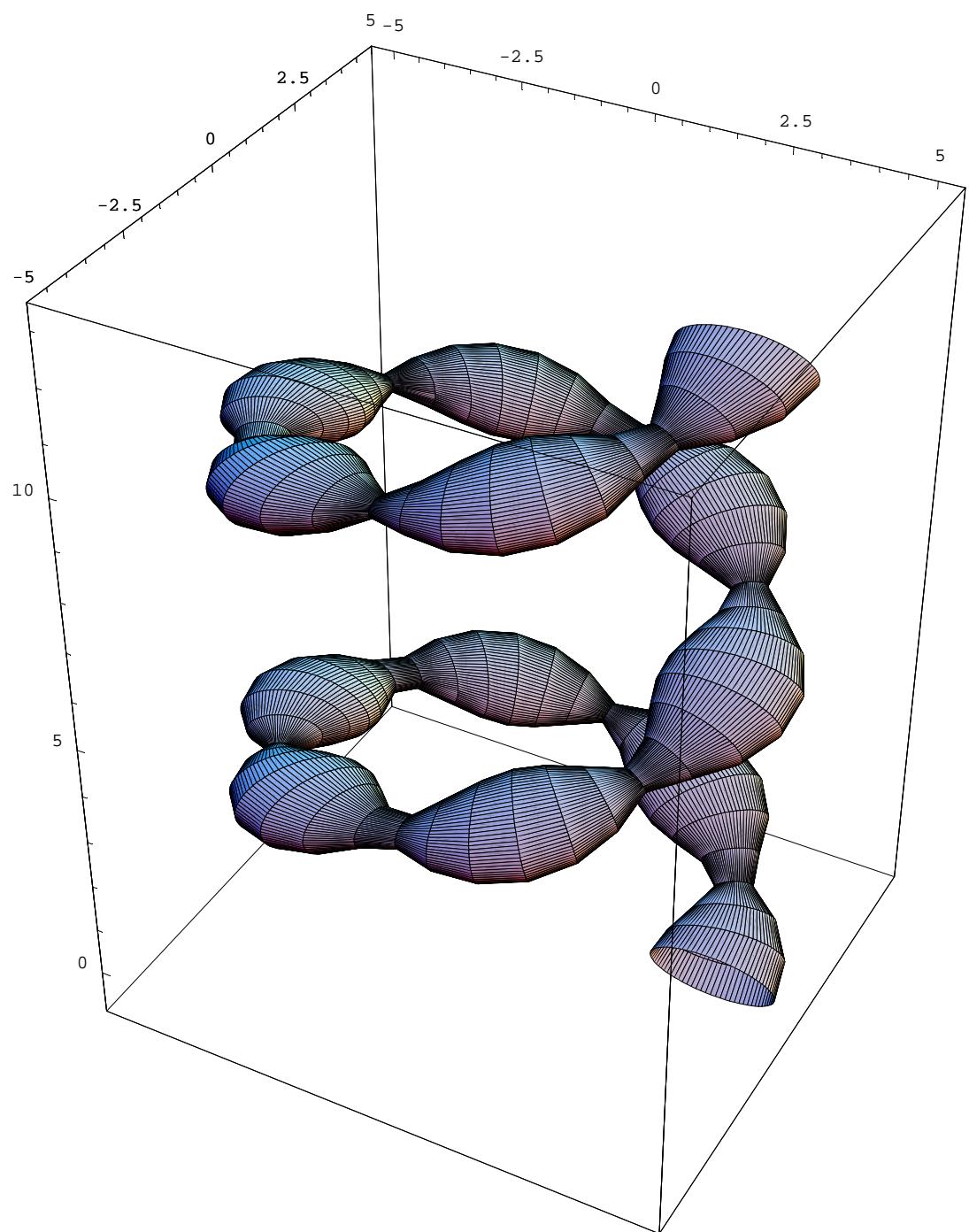
```
In[20]:= ParametricPlot3D[Evaluate[w[t,φ]],{t,0,4Pi},{φ,0,2Pi},PlotPoints→80];
```



**2**

```
In[83]:= (*Schlauchdefinitionen*)x[t_]:=4Cos[t];y[t_]:=4Sin[t];z[t_]:=t;
a[t_,φ_]:=(Abs[Cos[3t]]+0.2);b[t_,φ_]:=(Abs[Cos[3t]]+0.2)/2;
from[uhu];
ParametricPlot3D[Evaluate[w[t,φ]],{t,0,4Pi},{φ,0,2Pi},PlotPoints→80];
```



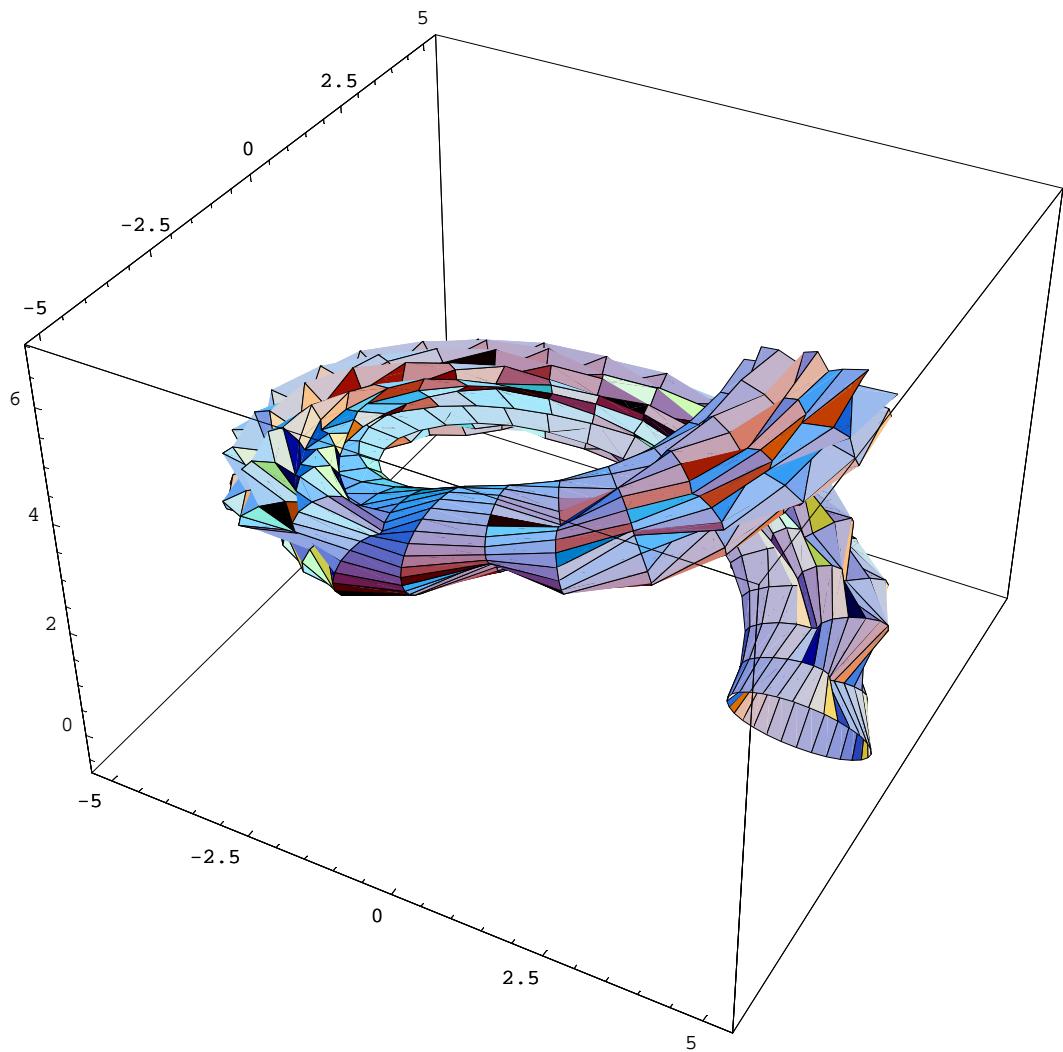


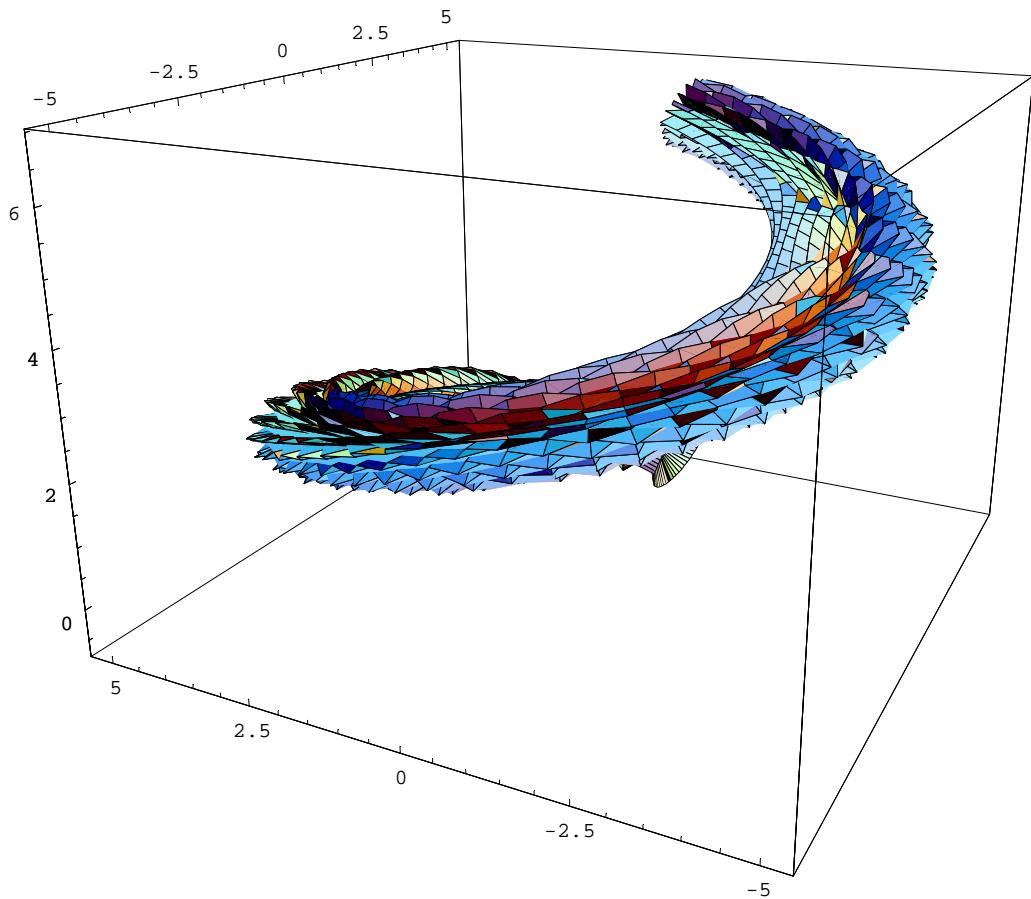
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## Ergebnisse von Untersuchungen der Klasse M2p: Schlauchdefinitionen für interessante Formen

1

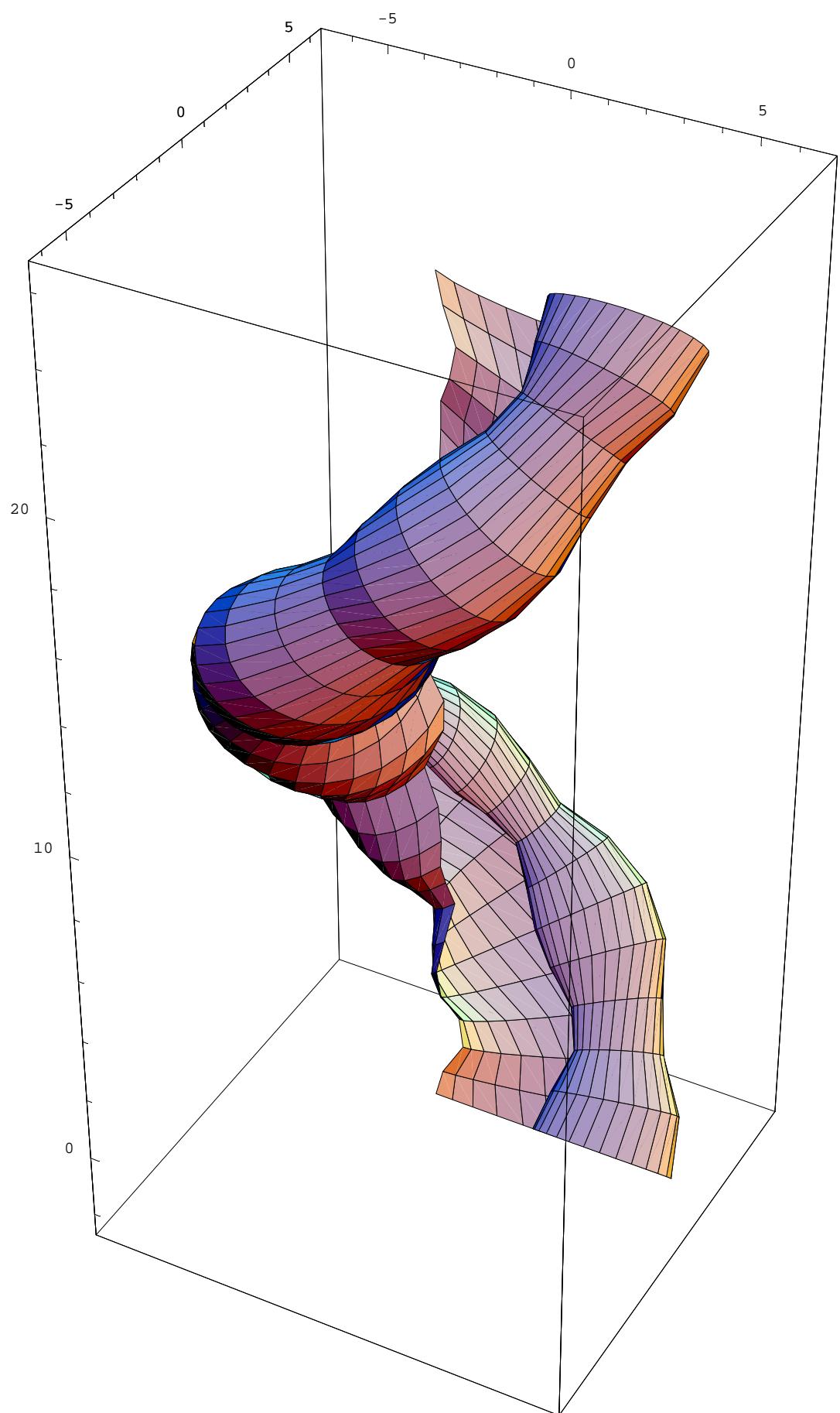
```
In[28]:= (*Schlauchdefinitionen*)
x[t_] = 4 Cos[t]; y[t_] := 4 Sin[t]; z[t_] := t;
a[t_, φ_] := (Abs[Cos[3 t φ]] + 0.2); b[t_, φ_] := (Abs[Cos[3 t φ]] + 0.2) / 2;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 2 Pi},
{φ, 0, 2 Pi}, ViewPoint -> {-1.735, -0.867, 0.664}, PlotPoints -> 60];
```

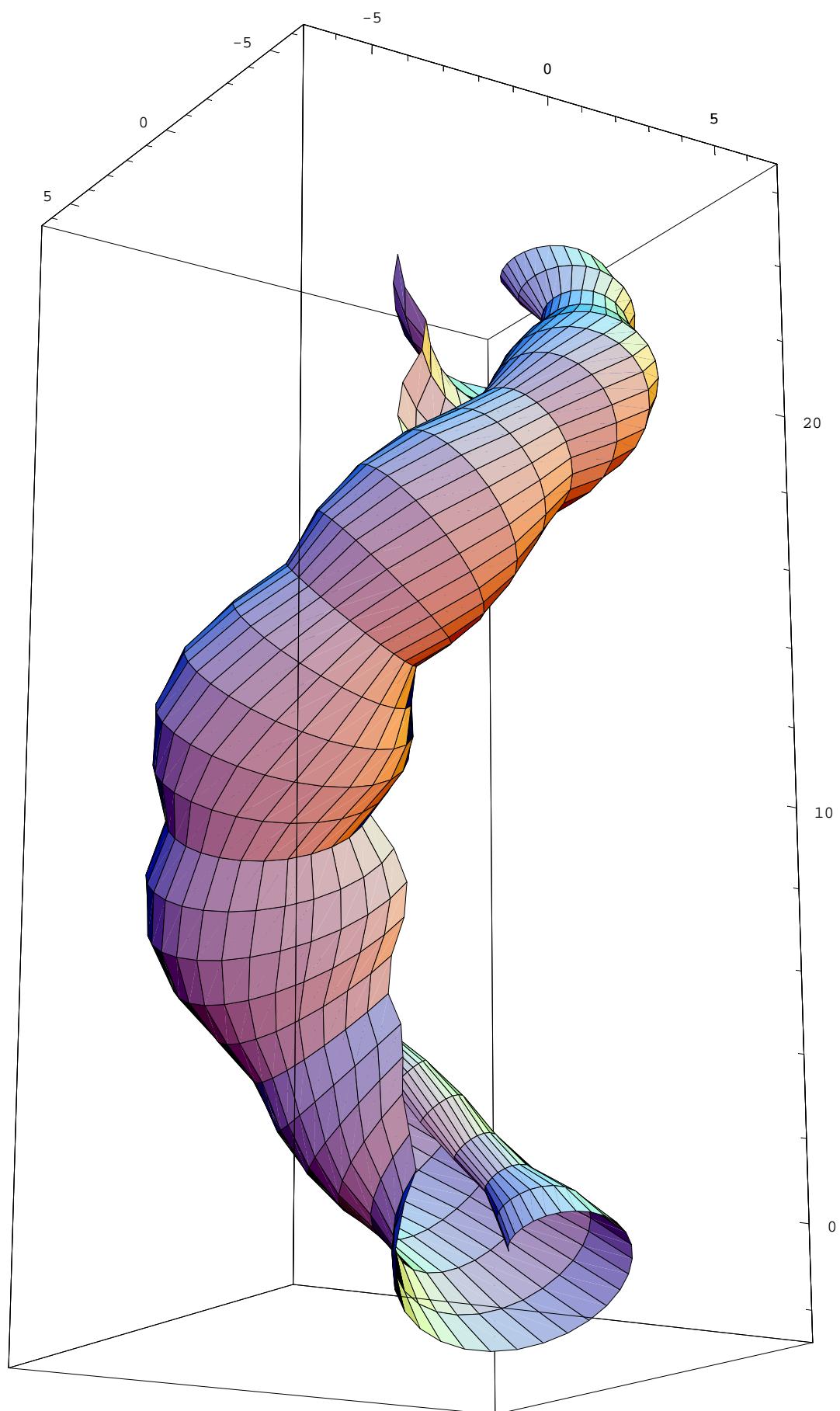




## 2

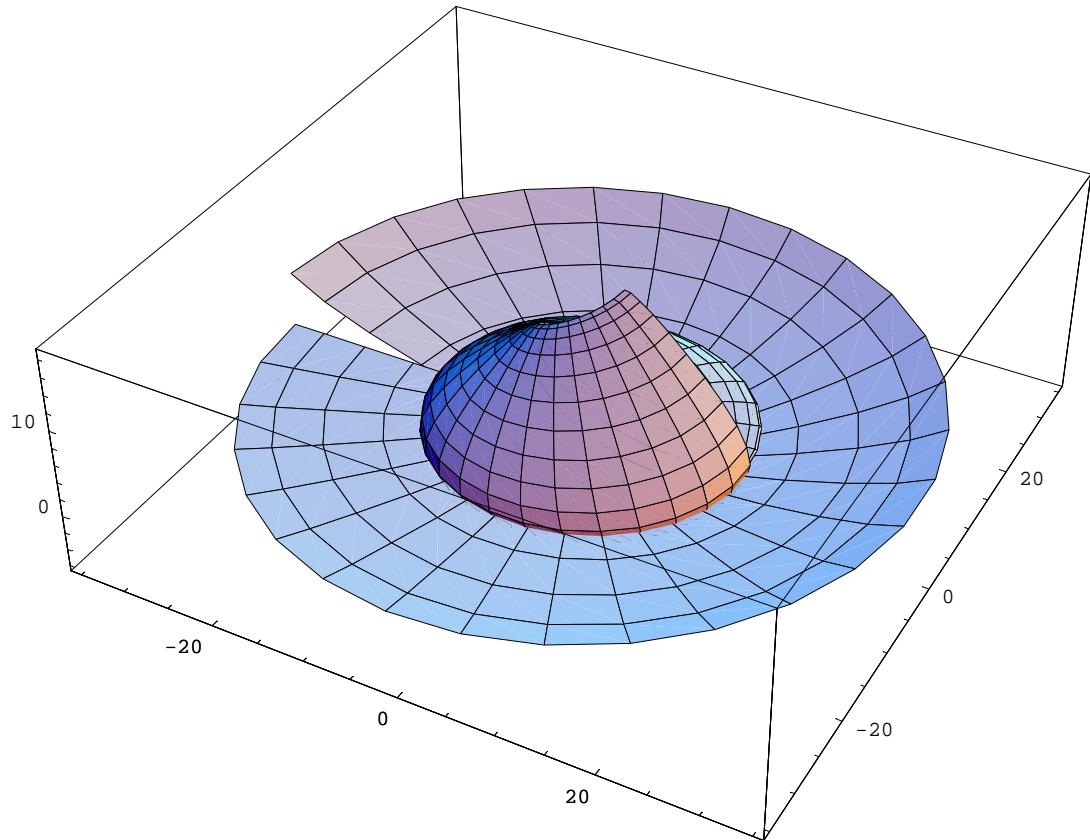
```
In[32]:= x[t_] := 4 Cos[t]; y[t_] := 4 Sin[t]; z[t_] := 4 t;
a[t_, φ_] := (Abs[Cos[3 t]] + 0.5 φ); b[t_, φ_] := (Abs[Cos[3 t]] + φ) / 2;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 2 Pi},
{φ, 0, 2 Pi}, ViewPoint -> {-1.730, -2.722, -1.025}];
```

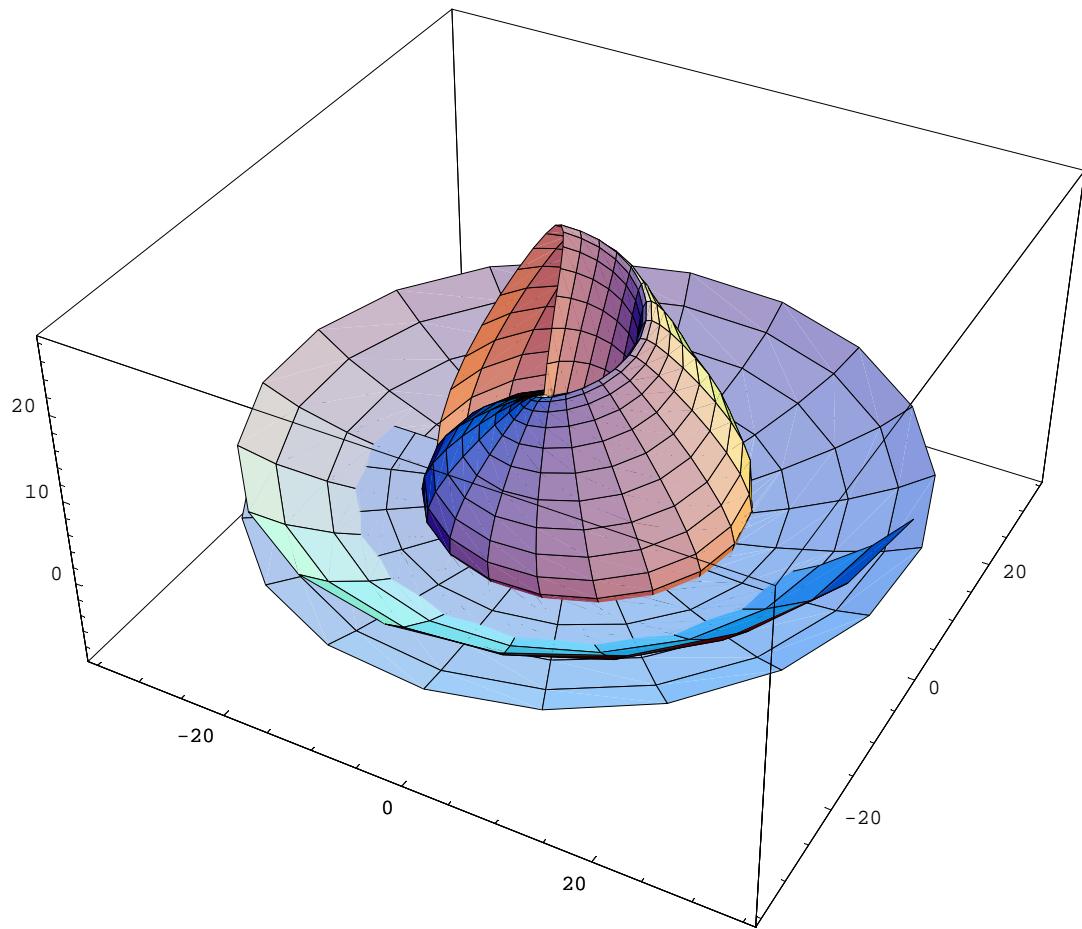




**3**

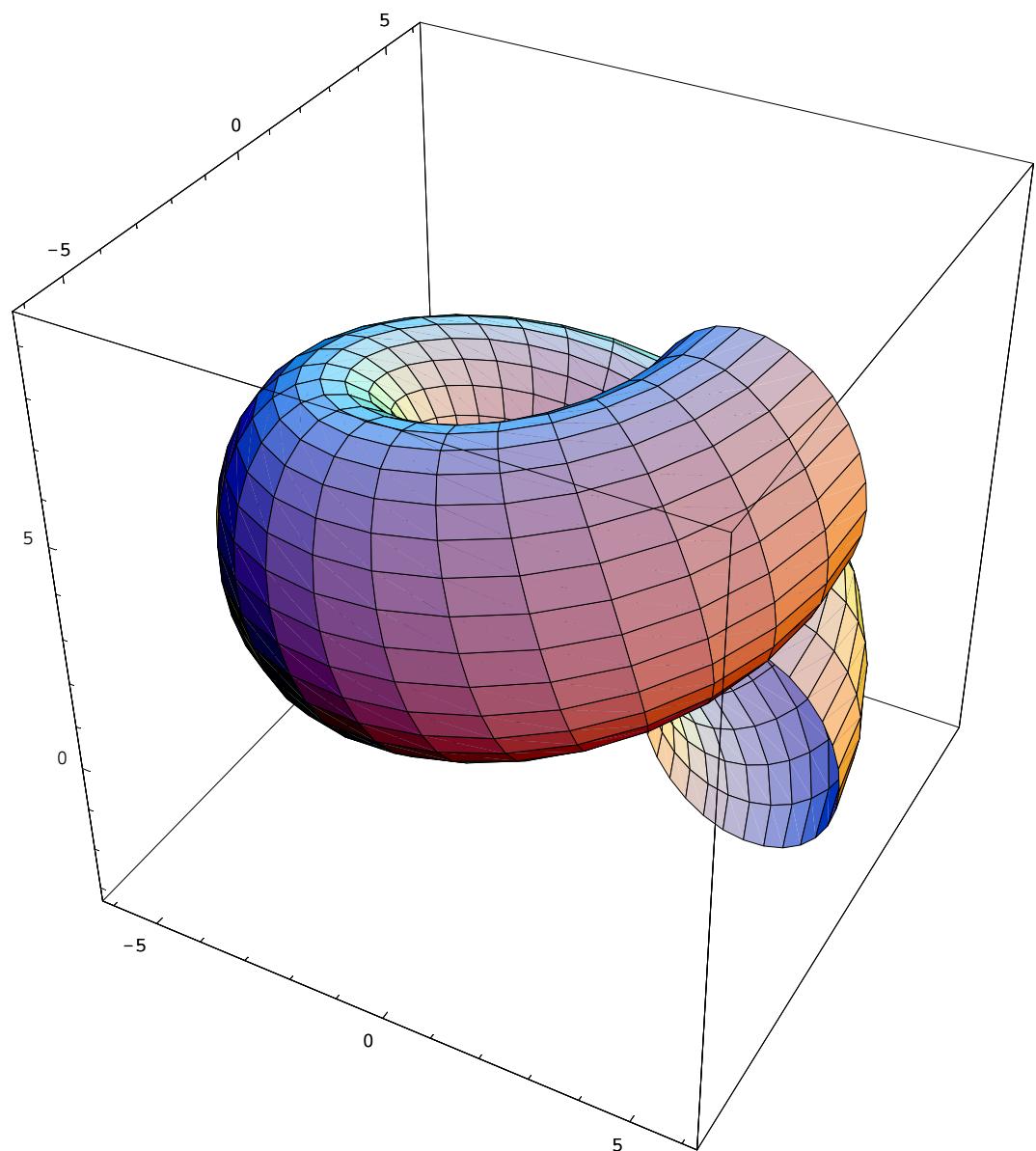
```
In[36]:= x[t_] := 5 Cos[t]; y[t_] := 5 Sin[t]; z[t_] := t;
a[t_, φ_] := φ^2; b[t_, φ_] := 2 t;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 3 Pi}, {φ, 0, 2 Pi}];
```

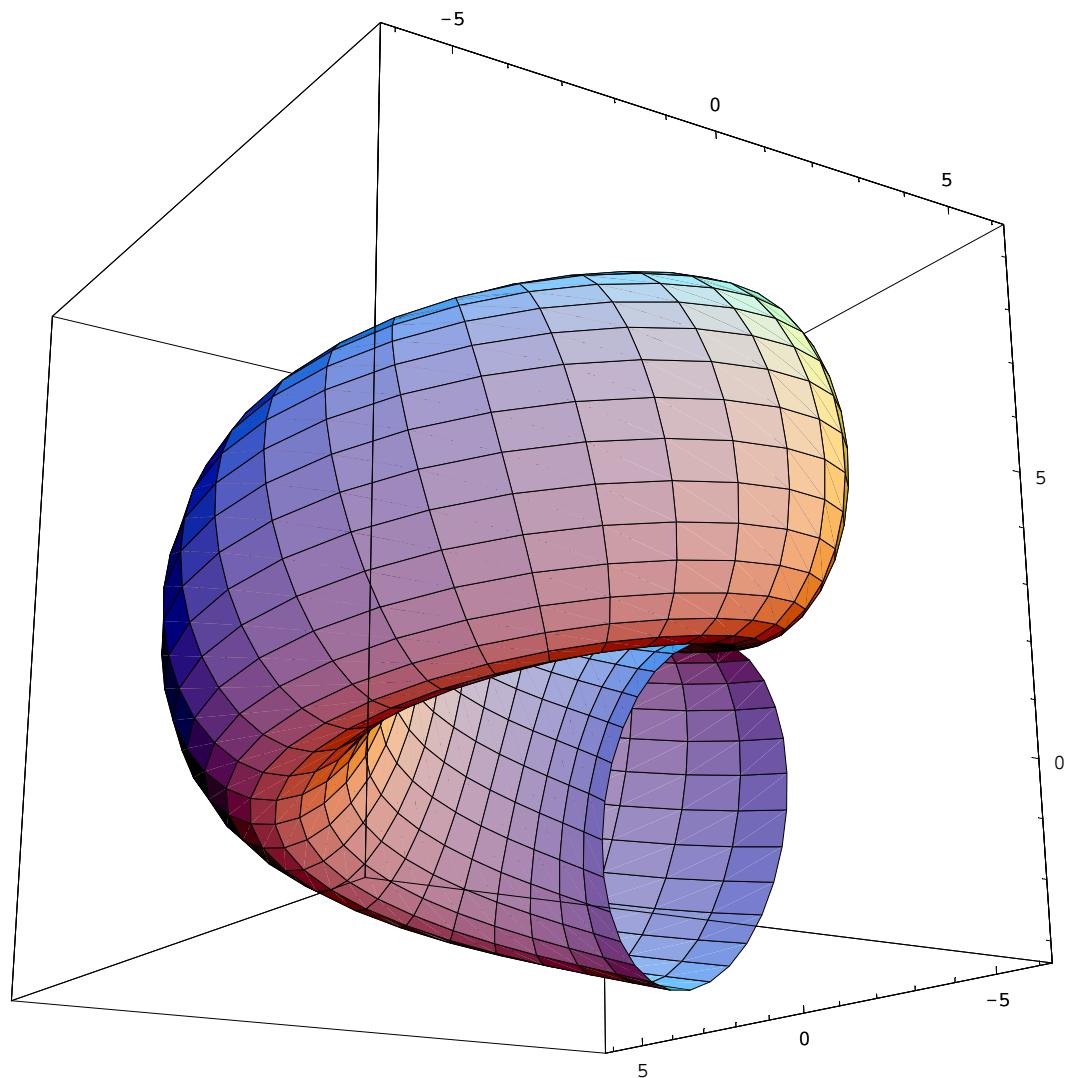




#### 4

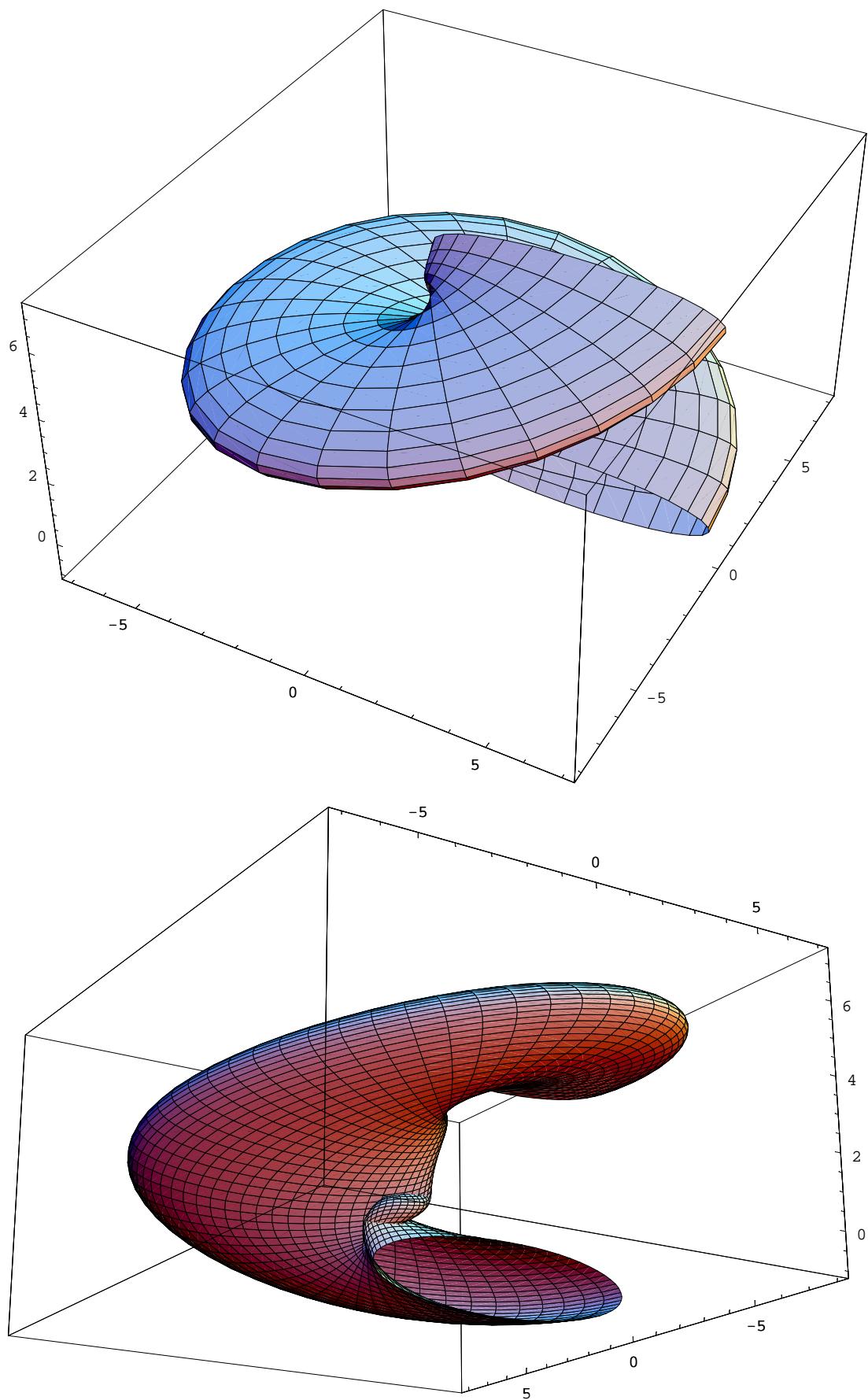
```
In[40]:= x[t_] = 4 Cos[t]; y[t_] := 4 Sin[t]; z[t_] := t;
a[t_, φ_] := 2; b[t_, φ_] := Pi;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 2 Pi},
{φ, 0, 2 Pi}, ViewPoint -> {-1.730, -2.722, -1.025}];
```





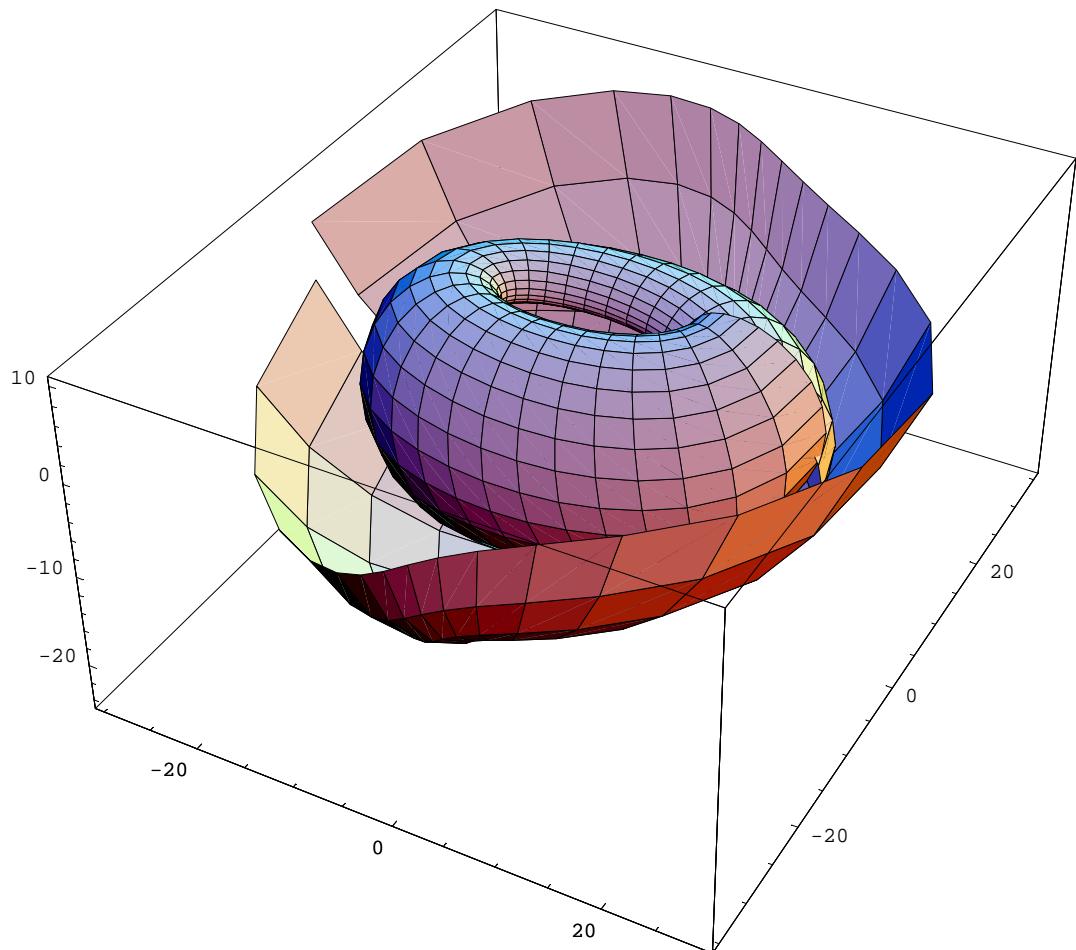
5

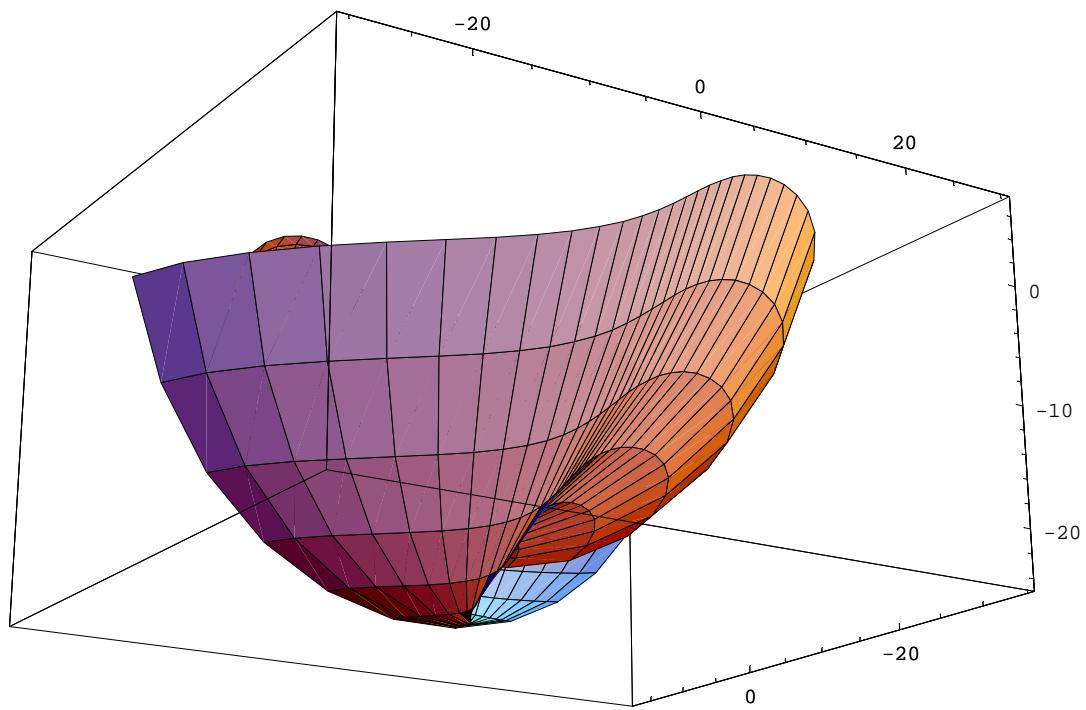
```
In[79]:= x[t_] = 3 Cos[t]; y[t_] := 4 Sin[t]; z[t_] := t;
a[t_, φ_] := 4; b[t_, φ_] := 1;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 2 Pi},
{φ, 0, 2 Pi}, ViewPoint -> {-1.730, -2.722, -1.025}, PlotPoints -> 60];
```



## 6

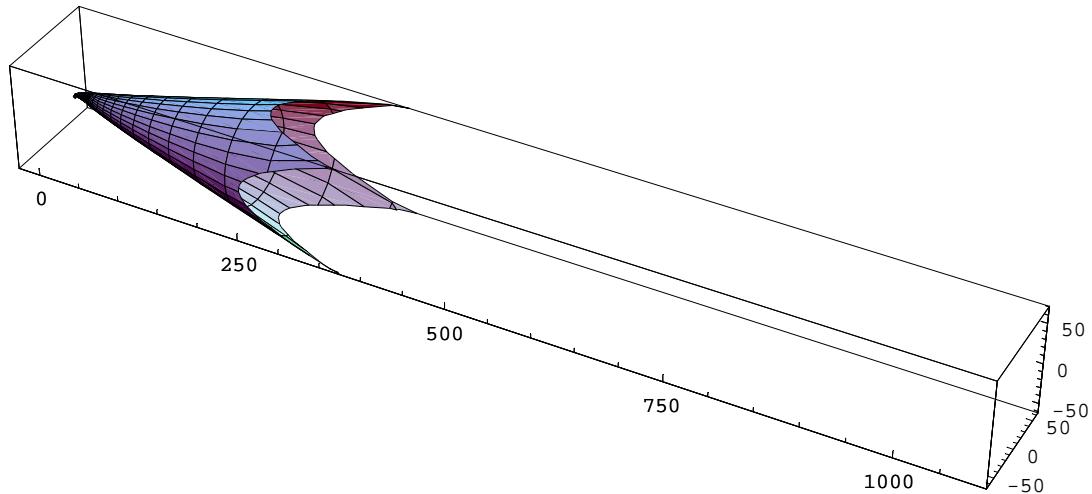
```
In[48]:= x[t_] := 10 Cos[t]; y[t_] := 5 Sin[t]; z[t_] := t;
a[t_, φ_] := φ^2; b[t_, φ_] := φ^2;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, Pi},
{φ, 0, 2 Pi}, ViewPoint -> {-1.730, -2.722, -1.025}];
```

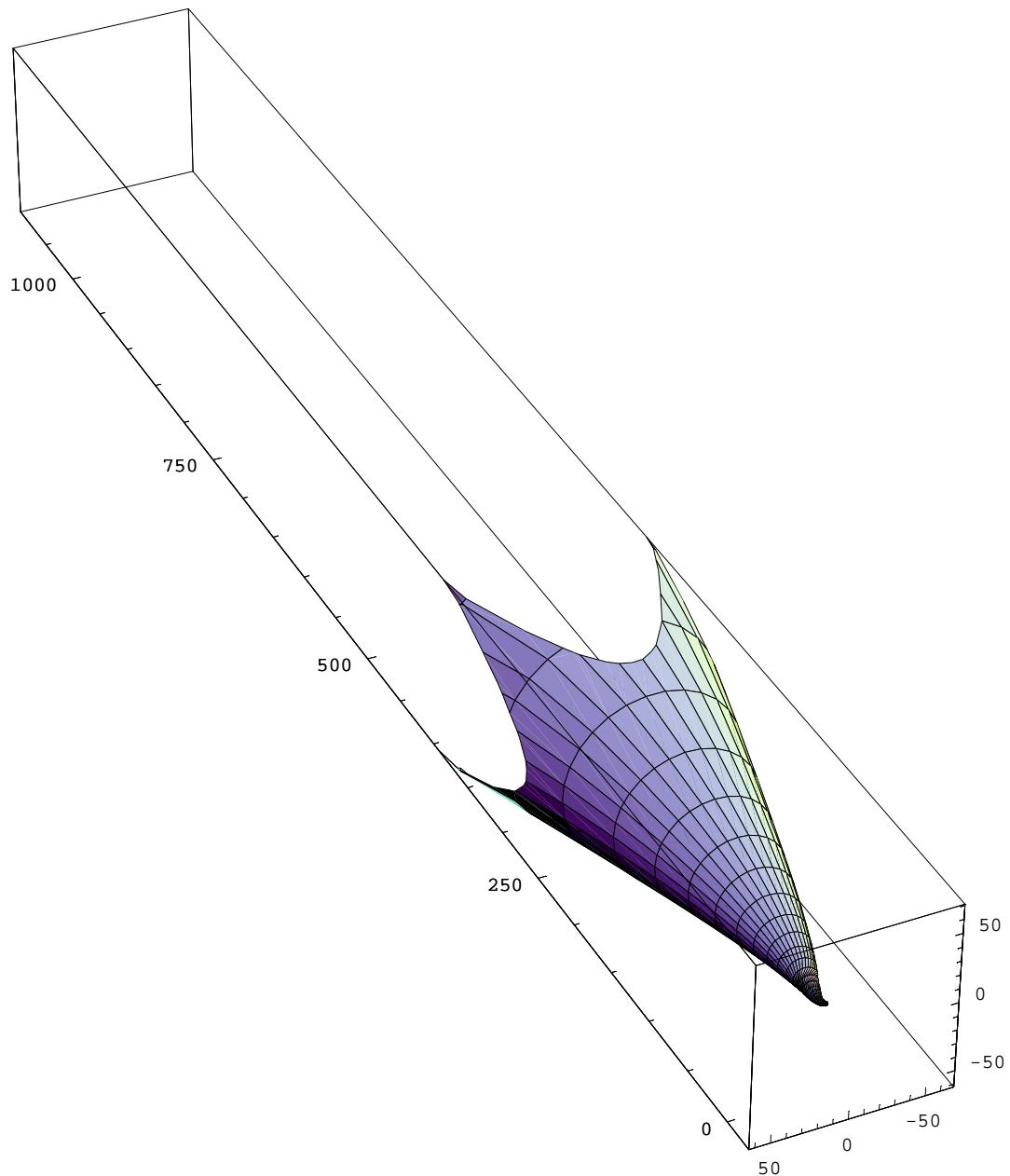




## 7 Bleistiftspitze

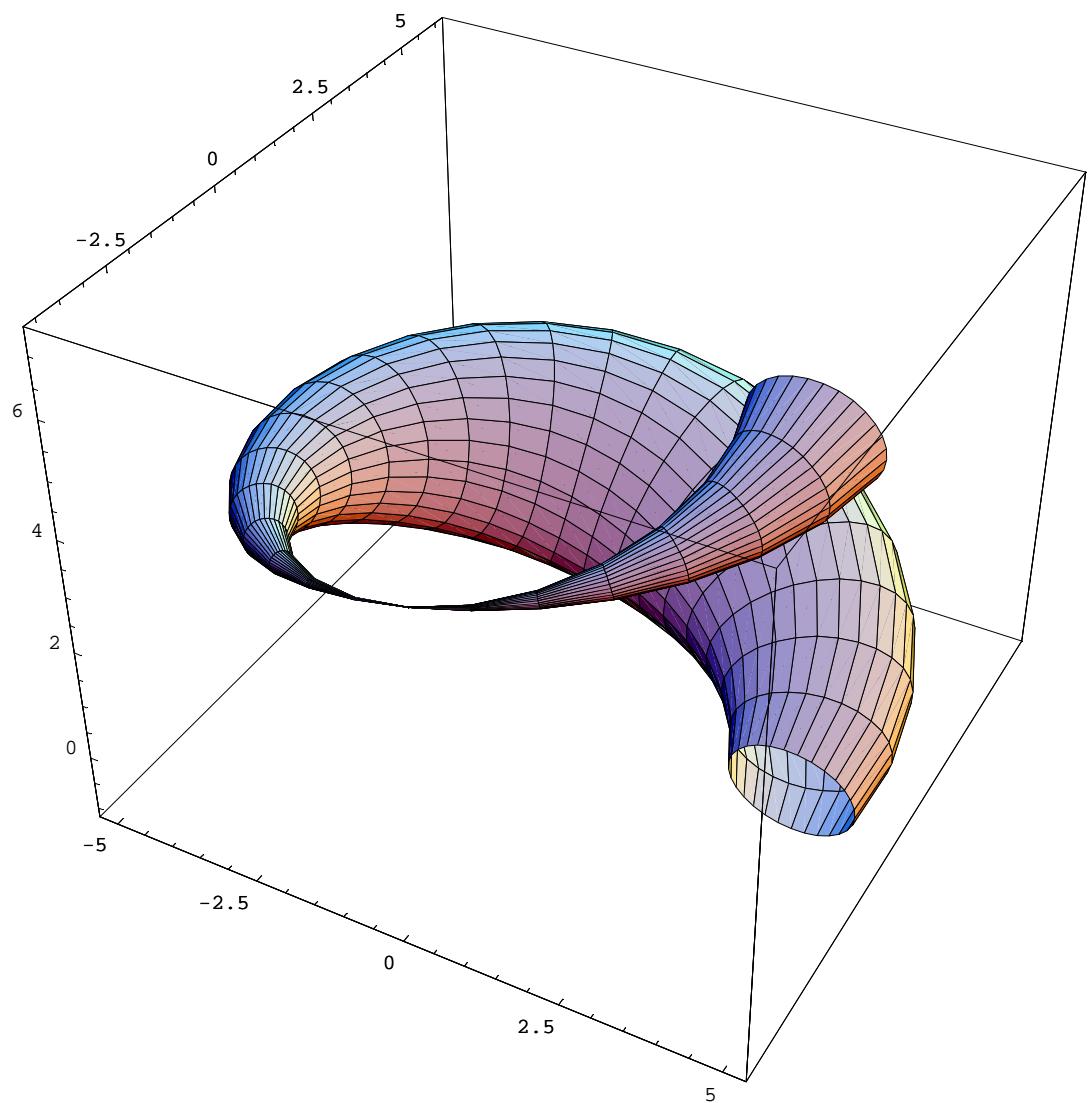
```
In[52]:= x[t_] = 4 Cosh[t]; y[t_] := 4 Sin[t]; z[t_] := t;
a[t_, φ_] := Sinh[t] + 1; b[t_, φ_] := Sinh[t] + 1;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]],
{t, 0, 2 Pi}, {φ, 0, 2 Pi}, ViewPoint -> {-2.540, 1.173, 1.904}];
```

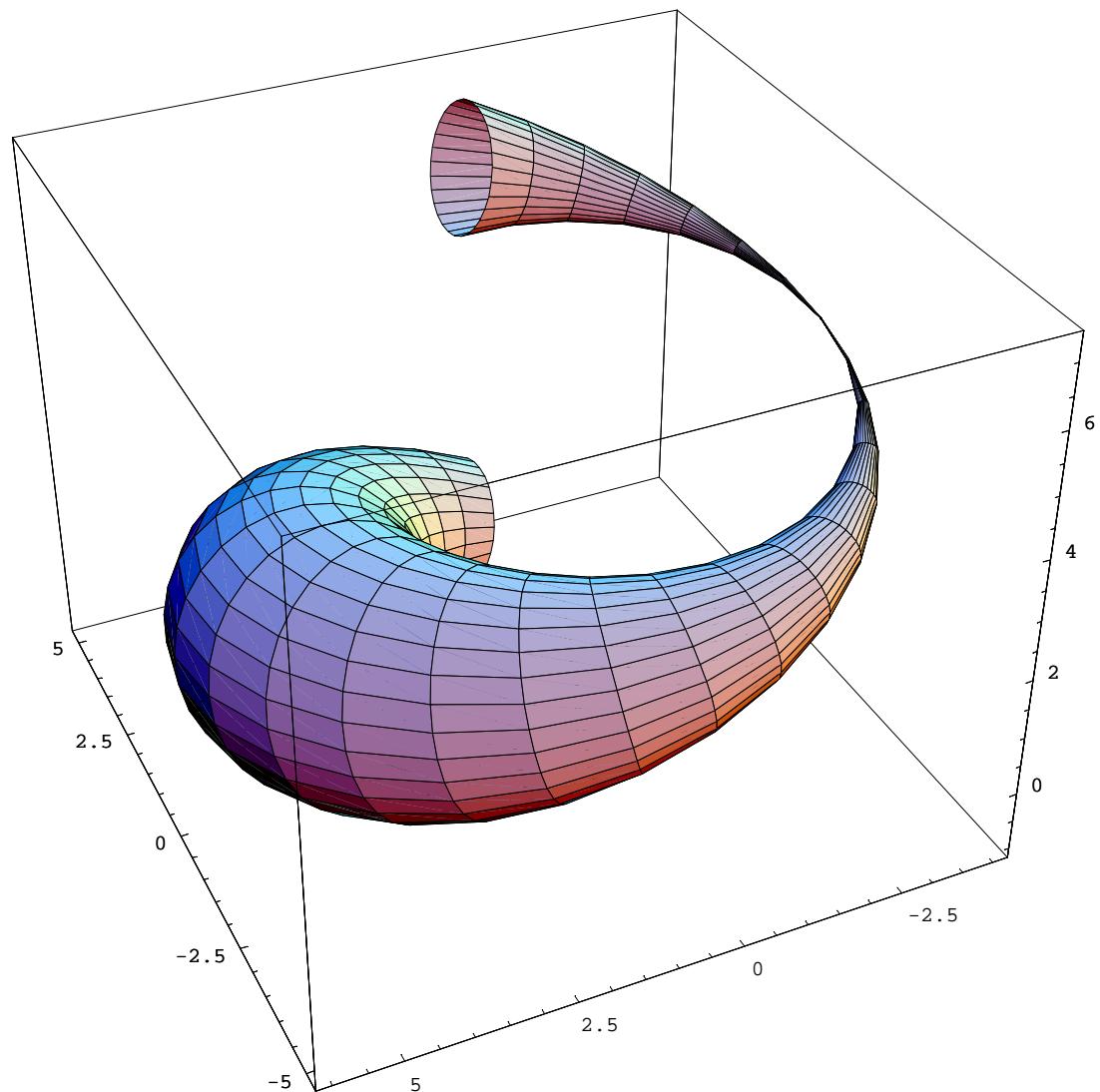




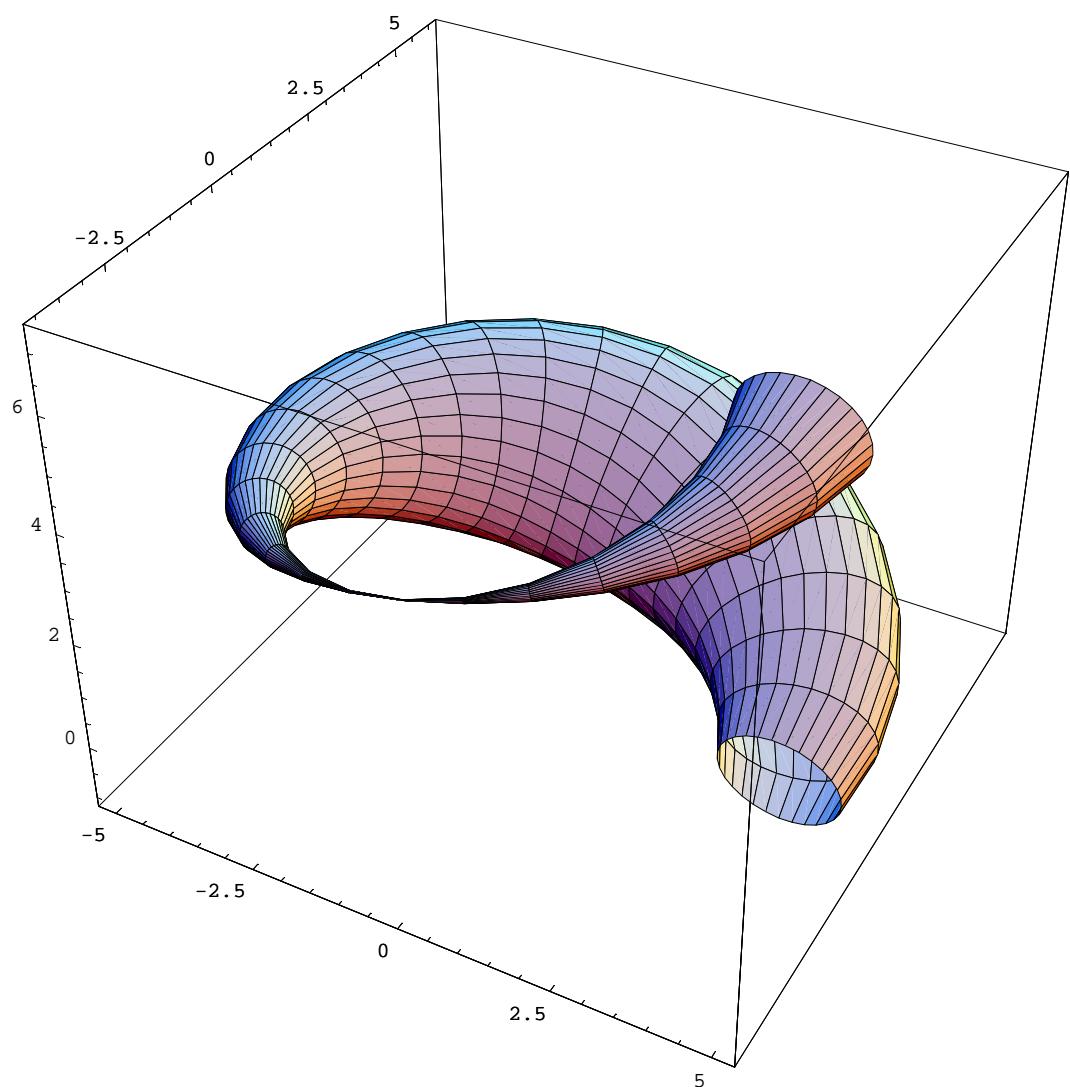
## 8 Wirrwar

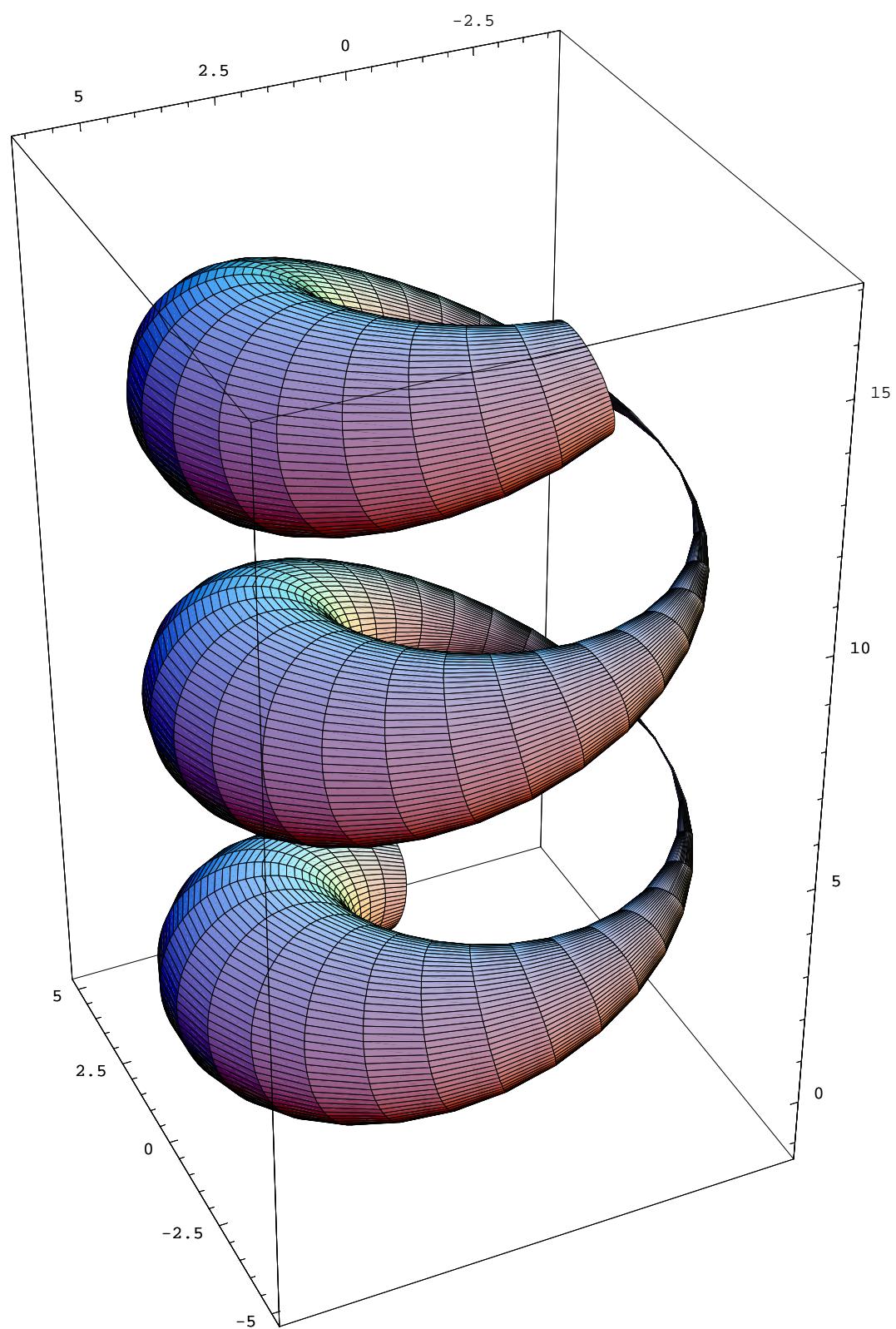
```
In[56]:= x[t_] = 4 Cos[t]; y[t_] := 4 Sin[t]; z[t_] := t;
a[t_, φ_] := Sin[t] + 1; b[t_, φ_] := Sin[t] + 1;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]],
{t, 0, 2 Pi}, {φ, 0, 2 Pi}, ViewPoint -> {-2.540, 1.173, 1.904}];
```



**9**

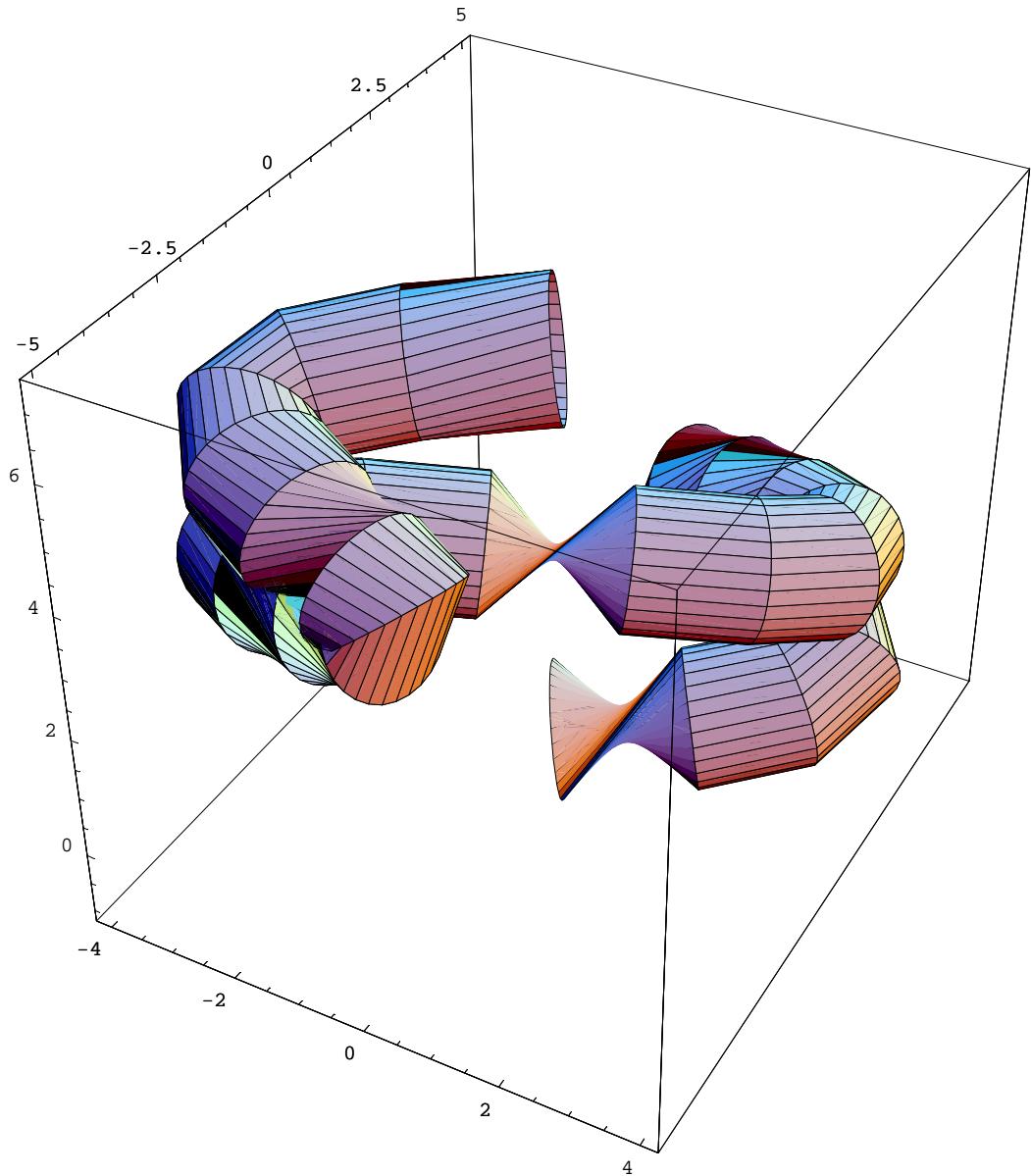
```
In[60]:= x[t_] = 4 Cos[t]; y[t_] := 4 Sin[t]; z[t_] := t;
a[t_, φ_] := Sin[t] + 1; b[t_, φ_] := Sin[t] + 1;
from[uhu];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 5 Pi},
{φ, 0, 2 Pi}, ViewPoint -> {-2.540, 1.173, 1.904}, PlotPoints -> 80];
```

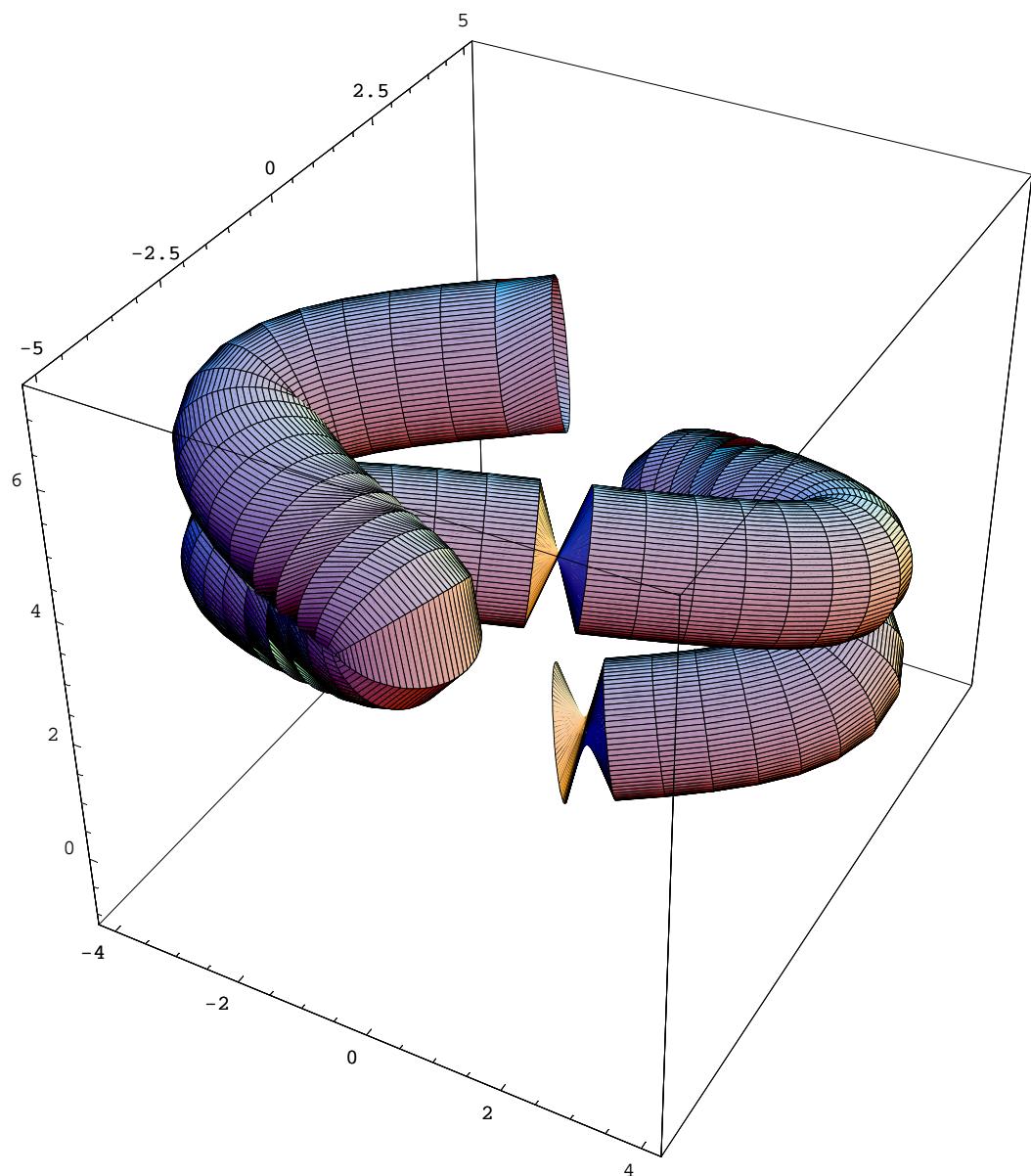




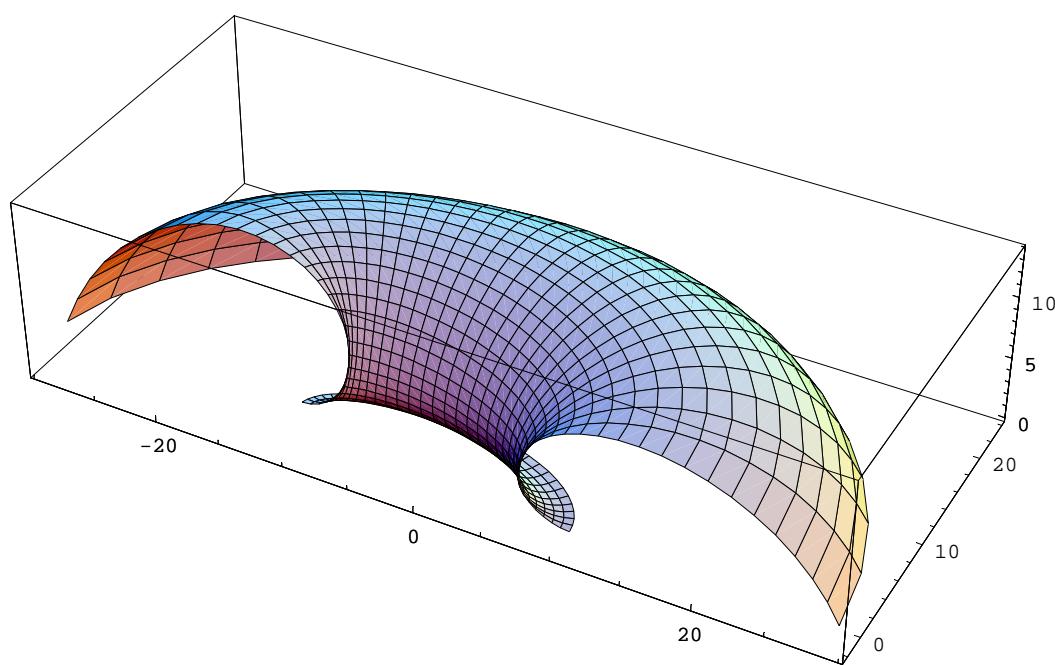
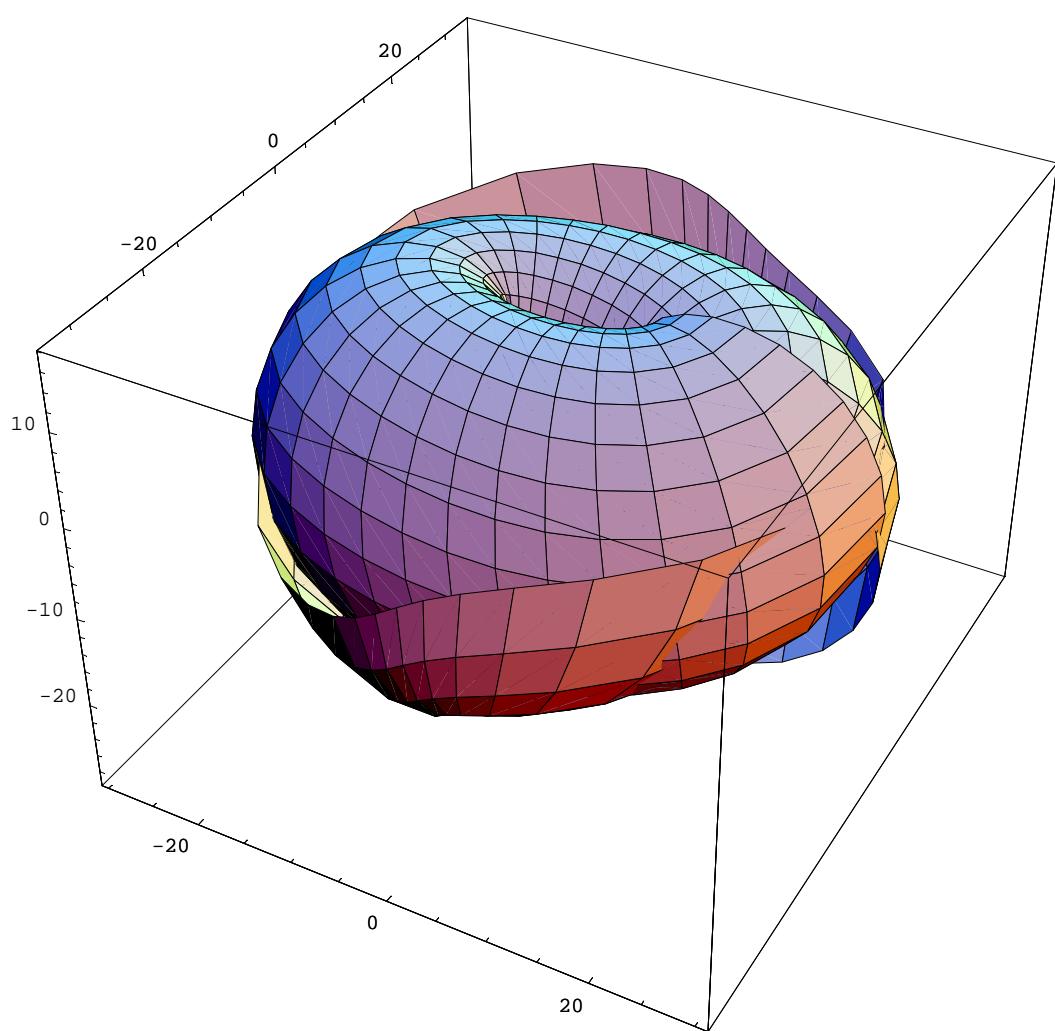
**10**

```
In[64]:= x[t_] = 4 Cos[t] Sin[2 t]; y[t_] := 4 Sin[t + 0.01]; z[t_] := t;
a[t_, φ_] := 1; b[t_, φ_] := 1;
from[uhu_];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 2 Pi}, {φ, 0, 2 Pi}, PlotPoints → 80];
```



**11**

```
In[68]:= x[t_] = 10 Cos[t]; y[t_] := 5 Sin[t]; z[t_] := t;
a[t_, φ_] := 3 φ*2; b[t_, φ_] := 3 φ*2;
from[uhu_];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, Pi}, {φ, 0, Pi}];
```



**12**

```
In[72]:= x[t_] := 10 Cos[t]; y[t_] := 5 Sin[t]; z[t_] := t;
a[t_, φ_] := φ*-2; b[t_, φ_] := 3 φ*2; from[uhu_];
ParametricPlot3D[Evaluate[w[t, φ]], {t, 0, 5/4 Pi}, {φ, 0, 5/4 Pi}];
```

